

## Real and Complex Analysis

MTL122/ MTL503/ MTL506

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## 1. CONTINUITY AND UNIFORM CONTINUITY

**Definition 1.1.** Suppose  $(X, d_X)$ ,  $(Y, d_Y)$  are metric spaces. A function  $f : X \rightarrow Y$  is continuous at the point  $a \in X$  if for every  $\epsilon > 0$  there exists  $\delta > 0$  such that  $x \in X$ ,  $d_X(x, a) < \delta$  implies  $d_Y(f(x), f(a)) < \epsilon$ .

A function is called **continuous** if it is continuous at all  $a \in X$ .

In terms of open balls, the definition says that  $f(B_\delta(a)) \subset B_\epsilon(f(a))$ .

**Definition 1.2.** A function  $f : A \rightarrow Y$  is continuous at  $c \in A \subset X$  if for every neighborhood  $V$  of  $f(c)$  there is a neighborhood  $U$  of  $c$  such that

$$x \in U \cap A \implies f(x) \in V.$$

Note that  $c$  must belong to the domain of  $f$  in order to define the continuity of  $f$  at  $c$ . If  $c$  is an isolated point of  $A$ , then the continuity condition holds automatically, since, for sufficiently small  $\delta > 0$ , the only point  $x \in A$  with  $d_X(x, c) < \delta$  is  $x = c$  and the  $0 = d_Y(f(x), f(c)) < \epsilon$ . Thus, a function is continuous at every isolated point of its domain, and isolated points are not of much interest.

A function is said to be Lipschitz continuous if there is  $C \in \mathbb{R}$  so that

$$d_Y(f(x), f(y)) \leq C d_X(x, y) \text{ for all } x, y \in X.$$

We also say that  $f$  is Lipschitz with constant  $C$ .

Lipschitz continuous map  $\implies$  continuous map.

**Solution:** Let  $\epsilon > 0$  and assume  $f : X \rightarrow Y$  be Lipschitz with constant  $C$ . Choose  $\delta < \frac{\epsilon}{C}$ . Now for any  $x_1, x_2 \in X$  such that  $d_X(x_1, x_2) < \delta$  we have

$$d_Y(f(x_1), f(x_2)) \leq C d_X(x_1, x_2) < C\delta < \epsilon.$$

This implies  $f$  is continuous.

Converse is not true.

**Example 1.3.** The function  $f : [0, \infty) \rightarrow \mathbb{R}$  defined by  $f(x) = \sqrt{x}$  is continuous but not Lipschitz.

Check:  $f$  is continuous.

Let  $0 < c < \infty$ . We will show that there exist choices of  $x, y \in [0, \infty)$  so that  $c|x - y| < |\sqrt{x} - \sqrt{y}|$ . Choose  $x = 0$  and  $y > 0$  such that  $c\sqrt{y} < 1$  which is guaranteed

by Archimedean property. Now we can rewrite this inequality as  $cy < \sqrt{y}$ . Then we can see that  $f$  is not Lipschitz.

$$c|y - x| = c|y - 0| = cy < \sqrt{y} = |\sqrt{y} - \sqrt{0}| = |\sqrt{y} - \sqrt{x}|.$$

**Example 1.4.** Let  $X = \mathbb{R} = Y$ , and let  $f : \mathbb{R} \rightarrow \mathbb{R}$  be the map

$$f(x) = \begin{cases} 0, & \text{if } x \in \mathbb{Q} \\ 1, & \text{if } x \notin \mathbb{Q}. \end{cases} \quad (1.1)$$

Let then  $d_{Euc}$  and  $d_{dis}$  be the Euclidean and the discrete metrics on  $\mathbb{R}$ . We have then

- $f : (X, d_{Euc}) \rightarrow (Y, d_{Euc})$  is not continuous;
- $f : (X, d_{Euc}) \rightarrow (Y, d_{dis})$  is not continuous;
- $f : (X, d_{dis}) \rightarrow (Y, d_{Euc})$  is continuous;
- $f : (X, d_{dis}) \rightarrow (Y, d_{dis})$  is continuous.

This describes the importance of keeping in mind which are the ambient metrics. As an exercise, fill in the details to show each of the points above.

**Example 1.5.** The function  $x \rightarrow d(x, A)$ , where  $\emptyset \neq A \subset X$  is continuous.

**Example 1.6.** Since  $|x_k - y_k| \leq d_{Euc}(x, y)$  for  $x, y \in \mathbb{R}^n$ , the projections  $x \in \mathbb{R}^n \rightarrow x_k$  are Lipschitz continuous.

One very important property of real-valued continuous functions from a metric space is that they can be added, multiplied, and multiplied by a scalar to get more continuous functions.

**Proposition 1.7.** Let  $(X, d)$  be a metric space,  $f, g : X \rightarrow \mathbb{R}$  be continuous, and  $c \in \mathbb{R}$ . Then  $f + g$ ,  $cf$  and  $f \cdot g$  are all also continuous functions from  $X$  to  $\mathbb{R}$ .

**Definition 1.8.** A function  $f : X \rightarrow Y$  is sequentially continuous at  $a \in X$  if  $x_n \rightarrow a$  in  $X$  implies that  $f(x_n) \rightarrow f(a)$  in  $Y$ .

**Theorem 1.9.** A function  $f : X \rightarrow Y$  is continuous at  $a$  if and only if it is sequentially continuous at  $a$ .

**Proof** Suppose that  $f$  is continuous at  $a \in X$ . Let  $\epsilon > 0$  be given and suppose that  $x_n \rightarrow a$ . Then there exists  $\delta > 0$  such that  $d(f(x), f(a)) < \epsilon$  for  $d(x, a) < \delta$ , and there exists  $N \in \mathbb{N}$  such that  $d(x_n, a) < \delta$  for  $n > N$ . It follows that  $d(f(x_n), f(a)) < \epsilon$  for  $n > N$ , so  $f(x_n) \rightarrow f(a)$  and  $f$  is sequentially continuous at  $a$ .

Conversely, suppose that  $f$  is not continuous at  $a$ . Then there exists  $\epsilon_0 > 0$  such that for every  $n \in \mathbb{N}$  there exists  $x_n \in X$  with  $d(x_n, a) < \frac{1}{n}$  and  $d(f(x_n), f(a)) \geq \epsilon_0$ . Then  $x_n \rightarrow a$  but  $f(x_n) \not\rightarrow f(a)$ , so  $f$  is not sequentially continuous at  $a$ .  $\square$

Recall that the pre-image of  $U$  under  $f$  is  $f^{-1}(U) = \{x : f(x) \in U\}$ . Note that use of  $f^{-1}$  does not mean that  $f$  has an inverse.

**Theorem 1.10.** A map  $f : X \rightarrow Y$  is continuous if and only if for every open(closed) set  $U \subset Y$ , the set  $f^{-1}(U)$  is open(closed) (in  $X$ ).

*Proof.* Suppose that the inverse image under  $f$  of every open set is open. Let  $U \subset Y$  open. Then by given condition  $f^{-1}(U) \subset X$  is open. Let  $y_0 \in U$  such that  $f(x_0) = y_0$ . Pick  $\epsilon > 0$  and consider  $U = B_\epsilon(f(x_0))$ . Since  $f^{-1}(U)$  is open, that is,  $f^{-1}(B_\epsilon(f(x_0)))$  is open, and  $x_0 \in f^{-1}(B_\epsilon(f(x_0)))$  so there exists  $\delta > 0$  such that  $B_\delta(x_0) \subset f^{-1}(B_\epsilon(f(x_0)))$  that is  $f(B_\delta(x_0)) \subset B_\epsilon(f(x_0))$ . Hence  $f$  is continuous.

Conversely, suppose that  $f : X \rightarrow Y$  is continuous and  $U \subset Y$  is open. We have to show that  $f^{-1}(U)$  is open. Take  $x_0 \in f^{-1}(U)$ . Then  $f(x_0) \in U$ . Since  $U$  is open there exists  $\epsilon > 0$  such that  $B_\epsilon(f(x_0)) \subset U$ . For this fixed  $\epsilon > 0$  we can use the continuity that is there exists  $\delta > 0$  such that  $f(B_\delta(x_0)) \subset B_\epsilon(f(x_0))$ . That is  $B_\delta(x_0) \subset f^{-1}(B_\epsilon(f(x_0))) \subset f^{-1}(U)$ , which implies  $x_0$  is an interior point and so  $f^{-1}(U)$  is open.  $\square$

- Any functions defined on a discrete metric spaces is always continuous.

**Theorem 1.11.** *The composition of continuous functions is continuous.*

*Proof.* Suppose that  $f : X \rightarrow Y$  and  $g : Y \rightarrow Z$  are continuous, and  $g \circ f : X \rightarrow Z$  is their composition. If  $W \subset Z$  is open, then  $V = g^{-1}(W)$  is open, so  $U = f^{-1}(V)$  is open. Now  $U = f^{-1}(g^{-1}(W))$  also  $(g \circ f)(U) = W$ , that is, the pre image of  $W$  under  $g \circ f$  is  $U$ . It follows that  $(g \circ f)^{-1}(W) = U$  is open. So  $g \circ f$  is continuous.  $\square$

### 1.1. Uniform Continuity.

**Definition 1.12.** *A function  $f : X \rightarrow Y$  is uniformly continuous if, for every  $\epsilon$ , there is a  $\delta > 0$  such that  $d_X(x, y) < \delta$  implies  $d_Y(f(x), f(y)) < \epsilon$ , for every  $x, y \in X$ .*

Spot the difference between uniform continuity and standard continuity? For standard continuity, for any  $\epsilon$ , we are allowed to find a  $\delta$  for each  $x$  such that  $d_X(x, y) < \delta$  implies  $d_Y(f(x), f(y)) < \epsilon$ . For uniform continuity you have to pick the same  $\delta$  for every  $x$ . Clearly, any uniformly continuous function is continuous, but, the reverse is not true. The key point of this definition is that  $\delta$  depends only on  $\epsilon$ , not on  $x, y$ .

- The function  $f(x) = 1/x$  is not uniformly continuous on  $(0, 1)$ .

*Proof.* It is known that  $f(x) = 1/x$  is continuous on  $(0, 1)$ . If we assume  $f(x) = 1/x$  is uniformly continuous on  $(0, 1)$ . Then there exists  $\delta > 0$  such that  $\forall x, y \in (0, 1)$  with  $|x - y| < \delta$ ,  $|\frac{1}{x} - \frac{1}{y}| < 1$ . Pick  $x \in (0, 1)$  with  $x < \delta$ . Then set  $y = \frac{x}{2}$ . Then  $|x - y| = \frac{x}{2} < \frac{\delta}{2} < \delta$ , and  $|\frac{1}{x} - \frac{1}{y}| = \frac{1}{x} > 1$ , a contradiction.  $\square$

**Exercise 1.13.** *If  $f : X \rightarrow Y$  is a Lipschitz continuous map between two metric spaces then  $f$  is uniformly continuous.*

*Proof.* Let  $f$  be a Lipschitz continuous map. By definition, there exists a constant  $K > 0$  such that

$$d_Y(f(x), f(y)) \leq Kd_X(x, y), \text{ for all } x, y \in X.$$

Now for any  $\epsilon > 0$ , let  $\delta(\epsilon) = \frac{\epsilon}{K}$ . Then  $d_X(x, y) < \delta(\epsilon)$  implies

$$d_Y(f(x), f(y)) \leq Kd_X(x, y) < K\delta(\epsilon) = \epsilon$$

for all  $x, y \in X$ . □

Converse is not true.

**Example 1.14.** *The function  $f(x) = \sqrt{x}$  is uniformly continuous on  $[0, \infty)$  but not Lipschitz.*

For any  $n \in \mathbb{N}$ ,  $|f(1/n) - f(0)| = \sqrt{1/n} = \sqrt{n}|1/n - 0|$ . It follows that  $f$  is not Lipschitz.

Given  $\epsilon > 0$ , let  $\delta = \epsilon^2$ . Suppose  $|x - y| < \delta$ , where  $x, y \geq 0$ . To estimate  $|f(x) - f(y)|$ , we consider two cases.

In the case  $x, y \in [0, \delta)$ , we use the fact that  $f$  is strictly increasing. Then  $|f(x) - f(y)| < f(\delta) - f(0) = \sqrt{\delta} = \epsilon$ . Otherwise, when  $x \notin [0, \delta)$  or  $y \notin [0, \delta)$ , we have  $\max(x, y) \geq \delta$ . Then

$$|\sqrt{x} - \sqrt{y}| = \left| \frac{x - y}{\sqrt{x} + \sqrt{y}} \right| \leq \frac{|x - y|}{2\sqrt{\max(x, y)}} < \frac{\delta}{\sqrt{\delta}} = \sqrt{\delta} = \epsilon.$$

Thus  $f$  is uniformly continuous.

## 2. COMPACTNESS IN METRIC SPACES

The closed intervals  $[a, b]$  of the real line and more generally the close bounded subsets of  $\mathbb{R}^n$  are compact. For these type of spaces we have seen interesting and very useful theorems like **Bolzano-Weierstrass theorem**, **Heine-Borel theorem** etc. Our aim to investigate the generalizations of these to metric spaces.

Let  $(X, d)$  be a metric space.

**Definition 2.1.** *A **covering** of  $X$  is a collection of sets whose union is  $X$ .*

**Definition 2.2.** *A collection of open sets  $\{U_i : i \in I\}$  in  $X$  is an open cover of  $Y \subset X$  if  $Y \subset \bigcup_{i \in I} U_i$ .*

*A subcover of  $\{U_i : i \in I\}$  is a sub-collection  $\{U_j : j \in J\}$  for some  $J \subset I$  that still covers  $Y$ . It is a finite subcover if  $J$  is finite.*

**Definition 2.3.**

(1) *A metric space  $X$  is **compact** if every open cover of  $X$  has a finite subcover.*

(2) *A metric space is **sequentially compact** if every sequence of points in  $X$  has a convergent subsequence to a point in  $X$ .*

**Example 2.4.**

(1)  *$(0, 1]$  is not sequentially compact and not compact. To show that  $(0, 1]$  is not compact, it is sufficient to find an open cover of  $(0, 1]$  that has no finite subcover. Consider  $U_n := (\frac{1}{n}, 2)$ , for  $n \in \mathbb{N}$ . We see,  $\bigcup_{n \in \mathbb{N}} U_n = (0, 2)$  and  $(0, 1] \subset (0, 2)$ . But if  $F$  is any finite subset of  $\{U_n : n \in \mathbb{N}\}$ . Let  $N \in \mathbb{N}$  such*

that  $F = \{U_{i_1}, U_{i_2}, \dots, U_{i_N}\}$ . Let  $k = \max\{i_1, i_2, \dots, i_N\}$ . Then  $U_k \in F$  and  $U_{i_j} \subseteq U_k$ , for  $i = 1, 2, \dots, N$ . and  $(0, 1] \not\subseteq \bigcup F = U_k = (\frac{1}{k}, 2)$ .

(2)  $[0, 1]$  is sequentially compact. In fact,  $[0, 1]$  is also compact.

(3)  $\mathbb{R}$  is neither compact nor sequentially compact. It is not sequentially compact or compact follows from the fact that  $\mathbb{R}$  from Heine-Borel.

### Exercise 2.5.

A nonempty subset  $K$  of a discrete metric space  $(X, d)$  is compact if and only if  $K$  is finite.

*Proof.* Assume that  $K$  is compact. Since each singleton set in a discrete metric space is open, the collection  $\mathcal{C} = \{\{x\} : x \in K\}$  is an open cover for  $K$ . Since  $K$  is compact, there are elements  $x_1, x_2, \dots, x_n$  in  $K$  such that  $K \subseteq \bigcup_{i=1}^n \{x_i\}$ . Hence  $K$  is finite.

Conversely, assume that  $K$  is finite. Then  $K$  is clearly compact as any finite set is compact.  $\square$

**Theorem 2.6.** A closed subset  $F$  of a compact metric space  $(X, d)$  is compact.

Easy.

**Theorem 2.7.** Every compact subset  $K$  of a metric  $(X, d)$  is closed and bounded.

*Proof.* If  $K = \phi$  then it is bounded. If not, the let  $x_0 \in K$ . Then let  $K \subseteq \bigcup_{n \in \mathbb{N}} B_n(x_0)$ .

By compactness there is a finite subset  $F \in \mathbb{N}$  such that  $K \subseteq \bigcup_{n \in F} B_n(x_0)$ . Let  $N$  be the largest integer in  $F$ . Such an integer exists because  $F$  is finite and non-empty. Then  $K \subset B_N(x_0)$  and it follows that  $K$  is bounded.

Let  $K$  be a compact subset of  $(X, d)$ . We shall prove  $X \setminus K$  is open. Fix a point  $p \in X \setminus K$ . For each  $x \in K$  consider  $\delta_x = \frac{1}{2}d(p, x)$ . Then  $\{B_{\delta_x}(x)\}_{x \in K}$  forms an open cover for  $K$ . Since  $K$  is compact, there exist  $x_1, x_2, \dots, x_k$  such that  $K \subseteq \bigcup_{i=1}^k B_{\delta_{x_i}}(x_i)$ .

Then  $V = \bigcap_{i=1}^k B_{\delta_{x_i}}(p)$  is an open set and contains  $p$ . Also since  $B_{\delta_{x_i}}(x_i) \cap B_{\delta_{x_i}}(p) = \phi$  for all  $i$  and so  $V \subset X \setminus K$ . Hence  $K$  is closed as  $X \setminus K$  is open.  $\square$

We know by Heine-Borel Theorem that a subset of  $\mathbb{R}$  is compact if and only if it is closed and bounded. That is, the converse of Theorem (2.7) holds if  $X = \mathbb{R}$ . But in general the converse doesn't hold.

**Example 2.8.**  $K$  be an infinite subset of a discrete metric space  $(X, d)$ . Then  $K$  is closed and bounded but not compact. (Exercise)

**Definition 2.9.** A subset  $A$  of a metric space  $X$  is totally bounded if, for every  $\epsilon > 0$ , there exist  $x_1, x_2, \dots, x_k \in A$ , with  $k$  finite, so that  $\{B_\epsilon(x_i) : 1 \leq i \leq k\}$  is an open

cover of  $X$ , that is,

$$A \subseteq \bigcup_{i=1}^k B_\epsilon(x_i)$$

**Example 2.10.** The set  $(0, 1)$  is totally bounded. For any  $\epsilon > 0$  by Archimedean property, there exists  $N \in \mathbb{N}$  such that  $N > \frac{1}{\epsilon}$ . Then consider the points  $\epsilon, 2\epsilon, \dots, (N - 1)\epsilon$ , and the balls  $B_\epsilon(n\epsilon)$ ,  $n = 0, 1, 2, \dots, N$ . Then  $(0, 1) \subset \bigcup_{n=1}^N B_\epsilon(n\epsilon)$ .

- A totally bounded set is bounded.

Let  $B$  be a totally bounded set. We can therefore cover  $B$  with finite number of  $\epsilon$ -balls, in particular with 1-balls.

$$B \subset \bigcup_{i=1}^N B_1(a_i).$$

Since there are only a finite number of these balls, we can find the maximum distance between their centres.  $D := \max\{d(a_i, a_j)\}$ . Now given any two points  $x, y \in B$ , they must be covered by two of these balls  $B_1(a_I)$  and  $B_1(a_J)$ , say. Therefore, using the triangle inequality twice,

$$d(x, y) \leq d(x, a_I) + d(a_I, a_J) + d(a_J, y) \leq 1 + D + 1.$$

That is  $D + 2$  is an upper bound for the distance between points in  $B$ .

But the converse is not true, i.e. bounded  $\not\Rightarrow$  totally bounded.

**Example 2.11.** Take  $U = \{e_n | n \in \mathbb{N}\} \subset l^\infty(\mathbb{R})$ , where  $e_n = (e_{nj})_{j \in \mathbb{N}}$  with  $e_{nj} = 1$ ,  $j = n$  and 0 otherwise. Then since  $\forall e_i, e_j \in U$   $d(e_i, e_j) = 1$  so obviously this set is bounded. But for  $\epsilon = 1$  we cannot find finite number of open balls with radius  $\epsilon$  that cover  $U$  - as each ball will contain only one element of  $U$ . Hence  $U$  is not totally bounded.

**Theorem 2.12.**  $X$  is totally bounded if and only if every sequence in  $X$  has a Cauchy subsequence.

*Proof.* First assume that  $X$  is totally bounded, and let  $\{x_n\}$  be a sequence in  $X$ .  $X$  is a union of finitely many sets of diameter less than 1. We pick one of these sets that contains infinitely many elements of  $(x_n)$  and call it  $S_1$ . Choose  $n_1$  such that  $x_{n_1} \in S_1$ . Again since  $S_1$  is totally bounded, it is a union of finitely many sets of diameter less than  $1/2$ . From here also we pick up a set that contains infinitely many elements of  $(x_n)$  and call it  $S_2$ . Choose  $n_2 > n_1$  such that  $x_{n_2} \in S_2$ . Continuing this way we get a decreasing sequence  $\{S_k\}$  of sets, that is  $S_k \supset S_{k+1}$ ,  $\forall k$ , of diameter less than  $1/k$  and a strictly increasing sequence  $\{n_k\}$  in  $\mathbb{N}$  such that  $x_{n_k} \in S_k$  for all  $k$ . Since  $d(x_{n_j}, x_{n_l}) < 1/k$  for all  $j, l \geq k$ , the subsequence is Cauchy.

Conversely, suppose  $X$  is not totally bounded. We will construct a sequence in  $X$  with no Cauchy subsequence. We can choose  $\epsilon > 0$  such that  $X$  is not finite union of open balls of radius  $\epsilon$ . Choose  $x_1 \in X$ . Since  $X \not\subseteq B_\epsilon(x_1)$ , we can choose  $x_2 \notin B_\epsilon(x_1)$ .

Similarly, we can choose  $x_3 \in \bigcup_{i=1}^2 B_\epsilon(x_i)$ . Continue in this way, getting a sequence  $\{x_n\}$  in  $X$  such that  $x_n$  in  $X$  such that

$$x_n \notin \bigcup_{i < n} B_\epsilon(x_i), \text{ for all } n.$$

It follows that if  $n \neq k$  then  $d(x_n, x_k) \geq \epsilon$ . Therefore,  $\{x_n\}$  has no Cauchy subsequence.  $\square$

**Theorem 2.13.** For a metric space  $(X, \rho)$ , the following are equivalent:

- (1)  $X$  is compact.
- (2)  $X$  is sequentially compact.
- (3)  $X$  is complete and totally bounded.

*Proof.* (1)  $\implies$  (2).

Let  $(x_n)$  be a sequence in a compact metric space  $X$ . If no subsequence of  $(x_n)$  converges in  $X$ , then for each  $y \in X$  there is some  $r_y > 0$  and a positive integer  $n_y$  such that  $x_n \notin B_{r_y}(y)$  for all  $n \geq n_y$ . Since  $X = \bigcup_{y \in X} B_{r_y}(y)$ , and  $X$  is compact so there are finitely many  $y_1, y_2, \dots, y_k \in X$  such that  $X = \bigcup_{i=1}^k B_{r_{y_i}}(y_i)$ . Take  $n_0 = \max\{n_{y_1}, n_{y_2}, \dots, n_{y_k}\}$ . Then  $x_{n_0+1} \notin B_{r_{y_i}}(y_i), \forall i = 1, 2, \dots, k$ . So  $x_{n_0+1} \notin X$ . A contradiction.

(2)  $\implies$  (3).

Suppose that every sequence in  $X$  has a convergent subsequence. Since a Cauchy sequence having a convergent subsequence is itself convergent so  $X$  is complete. Next assume that  $X$  is not totally bounded. Then there is some  $\epsilon > 0$  such that  $X$  cannot be covered by finitely many open balls of radius  $\epsilon$ . Let  $x_1 \in X$  and consider  $B_\epsilon(x_1)$  for some  $\epsilon > 0$ . Find  $x_2 \in X$  such that  $x_2 \notin B_\epsilon(x_1)$ . Inductively find  $x_{n+1} \in X$  such that  $x_{n+1} \notin \bigcup_{i=1}^n B_\epsilon(x_i)$ . Then by construction  $d(x_n, x_m) \geq \epsilon$  for all  $n, m = 1, 2, \dots$ , so  $(x_n)$  cannot have any convergent subsequence. A contradiction. Hence  $X$  is totally bounded.

(3)  $\implies$  (1).

Suppose that  $X$  is complete and totally bounded. Assume that  $X$  is not compact. Consider an open cover of  $X = \bigcup_{\alpha \in \Omega} \{U_\alpha\}$  without any finite subcover. Since  $X$  is totally bounded, cover  $X$  by finitely many open balls of radius 1. Then for at least one of these open balls of radius 1, say  $B_1(x_1)$  there exists no finite subcover. Now  $B_1(x_1) \subset X$  is totally bounded, cover  $B_1(x_1)$  by finitely many open balls of radius  $1/2$ . Then for at least one of these open balls of radius  $1/2$  there exists no finite subcover. So there exists  $x_2 \in B_1(x_1)$  such that  $B_{1/2}(x_2)$  has no finite subcover. Continuing this we get a sequence  $(x_n)$  in  $X$  with  $x_{n+1} \in B_{1/2^n}(x_n)$  such that  $B_{1/2^n}(x_n)$  has no

cover  $\frac{1}{2}$  radius ball  $\leftarrow B_1(x_1) \rightarrow$  no finite s.c.  
 $x_2 \in B_1(x_1)$  s.t.  $B_{1/2}(x_2) \rightarrow$  no finite s.c.

(can)  $x_m \in B_{1/2^{n+1}}(x_n)$   $B_{1/2}(a_2) \rightarrow$  cover by  $B_{1/2}$  ball.  
 $x_3 \in B_{1/2}(a_2)$  s.t.  $B_{1/2}(x_3)$  has no f. s.c. very

finite subcover. Now

S.t.  $B_{1/2^m}$

$$d(x_n, x_m) \leq \sum_{j=n}^{m-1} d(x_j, x_{j+1}) \leq \sum_{j=n}^{m-1} \frac{1}{2^j} \leq \frac{1}{2^{n-1}}$$

for all  $m > n$ . So  $(x_n)$  is a Cauchy sequence in the complete metric space  $X$ . Let  $x_n \rightarrow x \in X$ . Then  $x \in U_\alpha$  for some  $\alpha \in \Omega$ . Then there exists  $\epsilon > 0$  such that  $B_\epsilon(x) \subset U_\alpha$ . For this  $\epsilon > 0$  there exists  $N \in \mathbb{N}$  such that  $d(x_n, x) < \epsilon/2$  for all  $n \geq N$ . We choose  $m > N$  so large that  $1/2^m < \epsilon/2$ . Now let  $y \in B_{1/2^m}(x_m)$ , then

$$d(x, y) \leq d(x, x_m) + d(x_m, y) < \frac{\epsilon}{2} + \frac{1}{2^m} < \epsilon.$$

This implies  $y \in B_\epsilon(x)$ , that is  $B_{1/2^m}(x_m) \subset B_\epsilon(x) \subset U_\alpha$ . Thus  $U_\alpha$  constitutes a open subcover of  $B_{1/2^m}(x_m)$ . A contradiction to our construction of  $B_{1/2^m}(x_m)$ . □

**Theorem 2.14.** Let  $(X, d_1)$  and  $(Y, d_2)$  be metric spaces and  $f : X \rightarrow Y$  be a continuous function. Then for each compact subset  $C \subset X$ ,  $f(C) \subset Y$  is compact.

*Proof.* Let  $\{U_i : i \in I\}$  be an open cover of  $f(C)$ , and for each  $i \in I$ , define  $V_i = f^{-1}(U_i)$ . Notice that since  $f$  is continuous, each  $V_i$  is open and  $\{V_i : i \in I\}$  is an open cover of  $C$ . Since  $C$  is compact so it has a finite subcover  $\{V_{i_1}, \dots, V_{i_n}\}$ . Then  $\{U_{i_1}, U_{i_2}, \dots, U_{i_n}\}$  is a finite subcover of  $f(C)$ . This proves  $f(C)$  is compact. □

**Theorem 2.15.** Let  $f : (X, d_X) \rightarrow (Y, d_Y)$  be a continuous function of metric spaces, and suppose in addition that  $X$  is compact. Then  $f$  is uniformly continuous.

*Proof.* Let  $(X, d)$  be a compact metric space and  $(Y, \rho)$  be a metric space. Suppose  $f : X \rightarrow Y$  is continuous. We want to show that it is uniformly continuous.

Let  $\epsilon > 0$ . We want to find  $\delta > 0$  such that  $d(x, y) < \delta \implies \rho(f(x), f(y)) < \epsilon$  for all  $x, y \in X$ . Since  $f$  is continuous at each  $x \in X$  then there is some  $\delta_x > 0$  so that

$$f(B(x, \delta_x)) \subseteq B(f(x), \epsilon/2).$$

Now  $\{B(x, \delta_x/2)\}_{x \in X}$  is an open cover of  $X$  so there is a finite subcover  $\{B(x_i, \delta_{x_i}/2)\}_{i=1}^n$ .

Take  $\delta = \min_i(\frac{\delta_{x_i}}{2})$ . Suppose for  $x, y \in X$ ,  $d(x, y) < \delta$ . Since  $x \in X$  so  $x \in B(x_i, \delta_{x_i}/2)$  for some  $i$ . We claim then  $y \in B(x_i, \delta_{x_i})$ . (Check). Then for  $d(x, y) < \delta$  we have

$$\rho(f(x), f(y)) \leq \rho(f(x), f(x_i)) + \rho(f(x_i), f(y)) < \epsilon/2 + \epsilon/2 = \epsilon.$$

□

**Theorem 2.16.** Let  $(X, d_X)$  be a compact metric space. Then  $(X, d_X)$  is complete.

**Remark 2.17.** (Exercise)

- (1) The product of two compact metric spaces is compact.
- (2) A finite union of compact sets is compact.